

☐ 2 / 2

Patent Number:

JP61094829 A

19860513

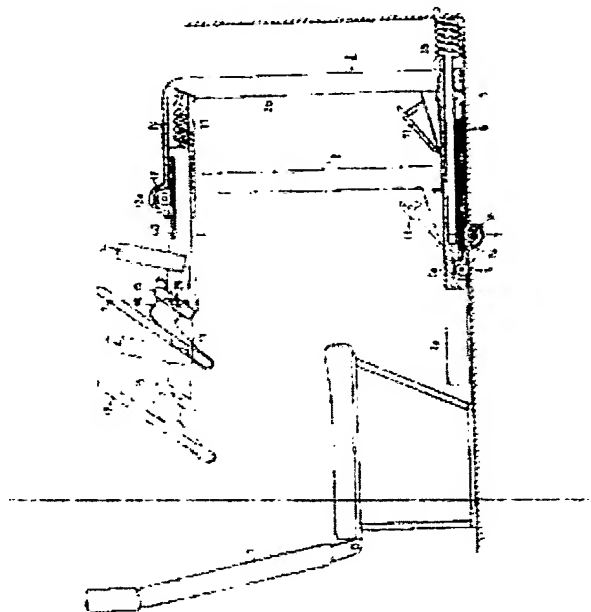
**AUTOMOBILE**

(JP61094829)

**PURPOSE:** To ensure an optimum control position, by a method wherein a pedalling type control body for running control is located to a control stand the position of which is longitudinally controllable, and a manual type control body for running control is located so that its position is adjustable independently from the pedalling type control body for running control.

**CONSTITUTION:** A distance between a driver seat 1 and a control stand 2 is decreased by forward-running a geared motor 7 through control of a switch. In which case, through engagement of a driving gear 7a with a rack 6, the control stage 2 is guided by a guide rod 9 and is moved backward. This causes a brake pedal and accel pedal 11 to be located to an optimum control position. Further, in order to set the control position of a handle 17 to an optimum spot, a geared motor 12 is run through control of a second switch. This causes a mounting body 13 to be moved in a manner to be guided by a guide hole 2c.

COPYRIGHT: (C)1986,JPO&amp;Japio



©Questel Orbit

**Inventor(s):** ITO MINORU  
NUMAZAWA MITSUO

**Patent Assignee:** TOYODA  
AUTOMATIC LOOM  
WORKS

**Orig. Patent Assignee:** (A) TOYODA AUTOM  
LOOM WORKS LTD

**FamPat family**

JP61094829	A	19860513 [JP61094829] Doc. Laid open to publ. Inspec.
STG:		1984JP-0215534
AP :		19841015

**Priority Details:** 1984JP-0215534  
19841015

©QUESTEL-ORBIT

BEST AVAILABLE COPY